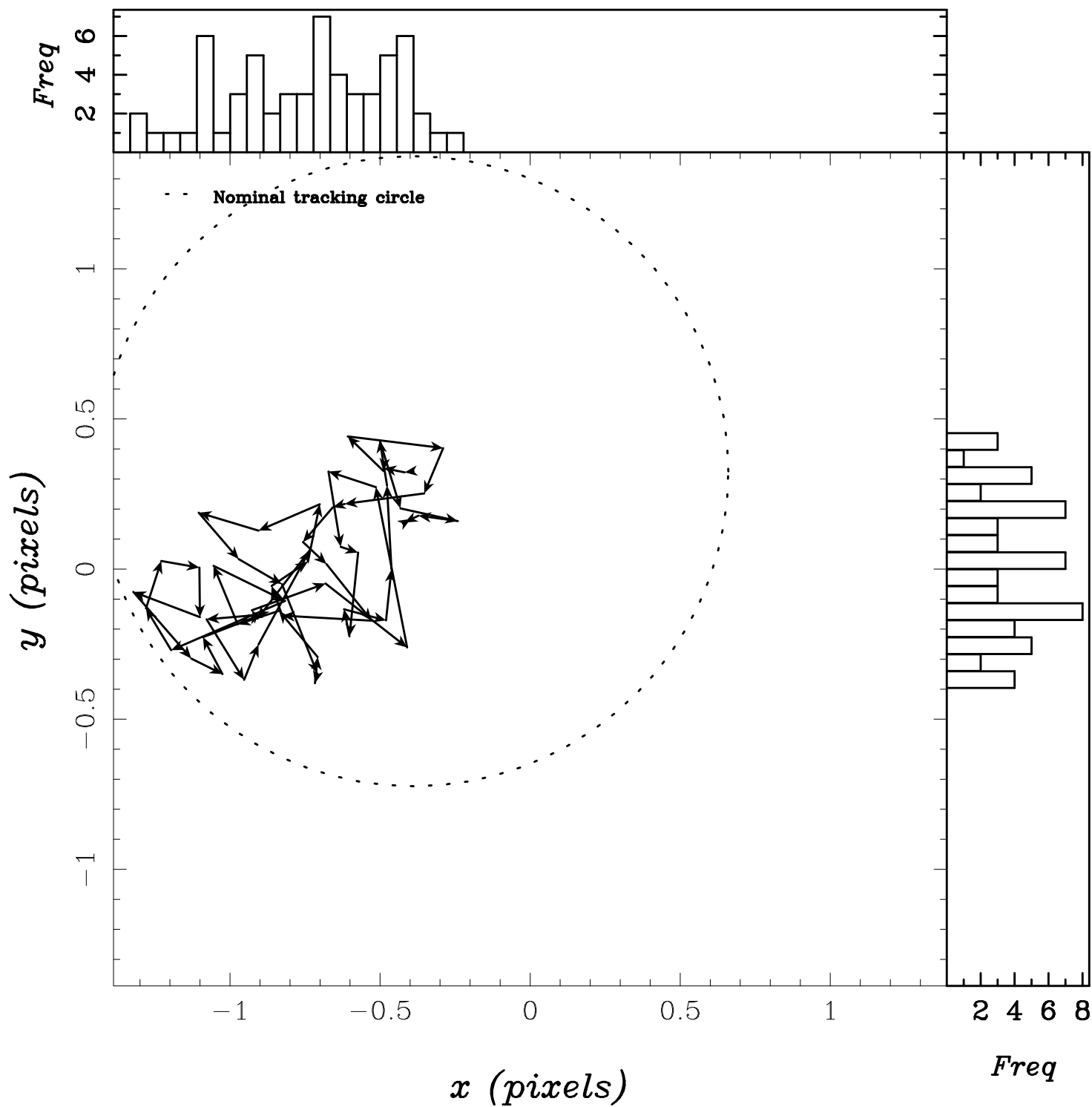


# OM tracking history plot– object EF Eri

Observation ID: 0111320201  
Exposure ID: 0111320201402  
Filter V Plate-scale=0.4765 arcsecs/pixel  
Tracking frame time: 20.0 secs  
Number of good tracking frames: 60  
Number of bad tracking frames: 0

*Tracking history vector plot*



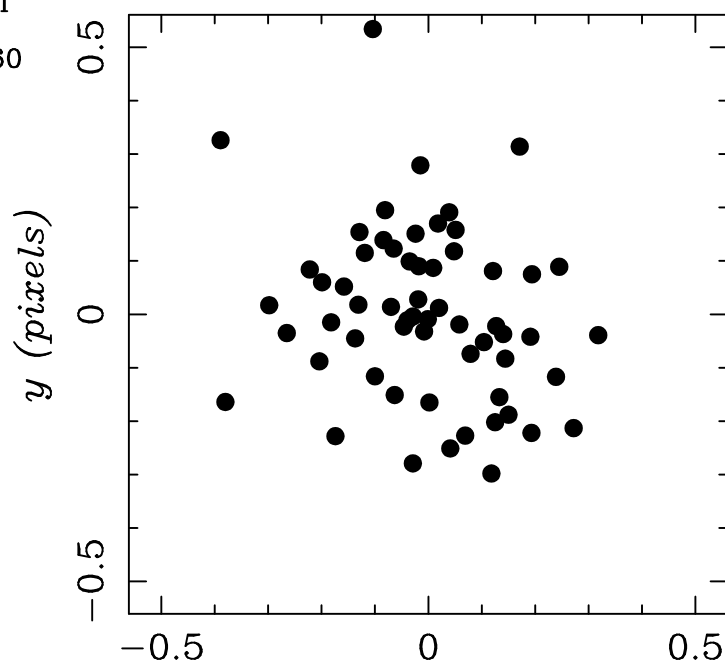
# OM tracking history plot– object EF Eri

Observation ID: 0111320201  
 Exposure ID: 0111320201402  
 Filter V Plate-scale=0.4765 arcsecs/pixel  
 Tracking frame time: 20.0 secs  
 Number of good tracking frames: 60  
 Number of bad tracking frames: 0

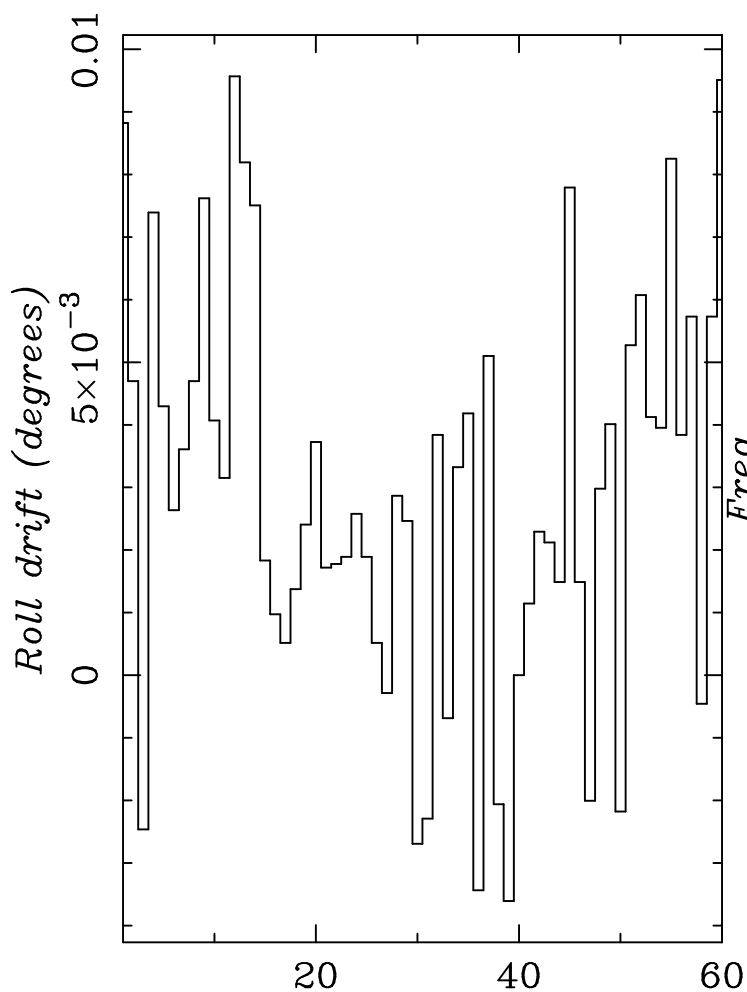
Percentage of excursions  
 outside 1.0 pixels: 20.0 %

Mean drift per tracking  
 frame (pixels): 0.2

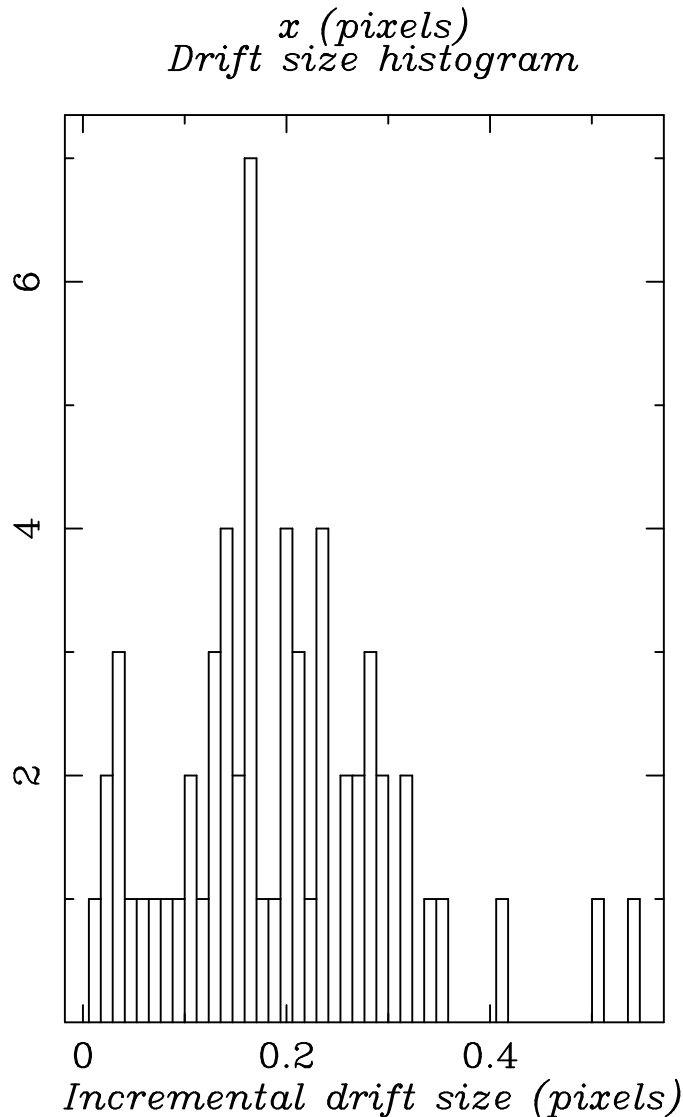
*Incremental drift spot diagram*



*Roll drift plot*



*Frame number*



*Incremental drift size (pixels)*