

Observation ID: 0150190301
Exposure ID: 0150190301403
Filter UVW1 Plate-scale=0.4765 arcsecs/pixel
Tracking frame time: 20.0 secs
Number of good tracking frames: 220
Number of bad tracking frames: 0

Number of good tracking frames: 22
Number of bad tracking frames: 0

Figure 1 is a 2D histogram showing the distribution of x and y coordinates for the nominal tracking circle. The x-axis is labeled x (pixels) and ranges from -1 to 1. The y-axis is labeled y (pixels) and ranges from -1 to 1. The histogram shows a dense cluster of points around the origin, with a dashed circle labeled "Nominal tracking circle" centered at (0,0). The distribution is roughly circular, with a peak frequency of about 15.

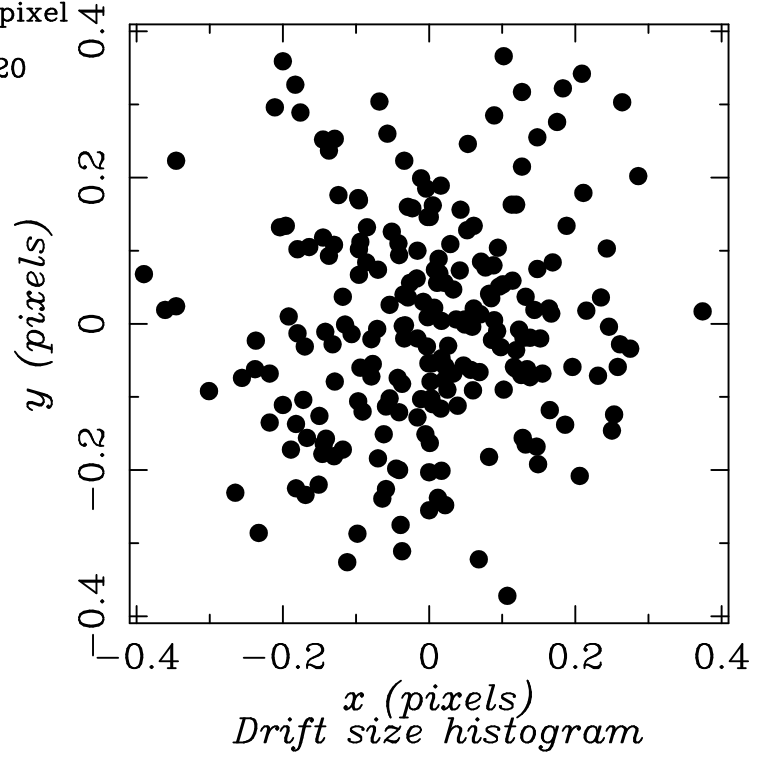
OM tracking history plot– object VV Pup

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Percentage of excursions
 outside 1.0 pixels: 0.0 %

Mean drift per tracking
 frame (pixels): 0.2

Incremental drift spot diagram



Roll drift plot

