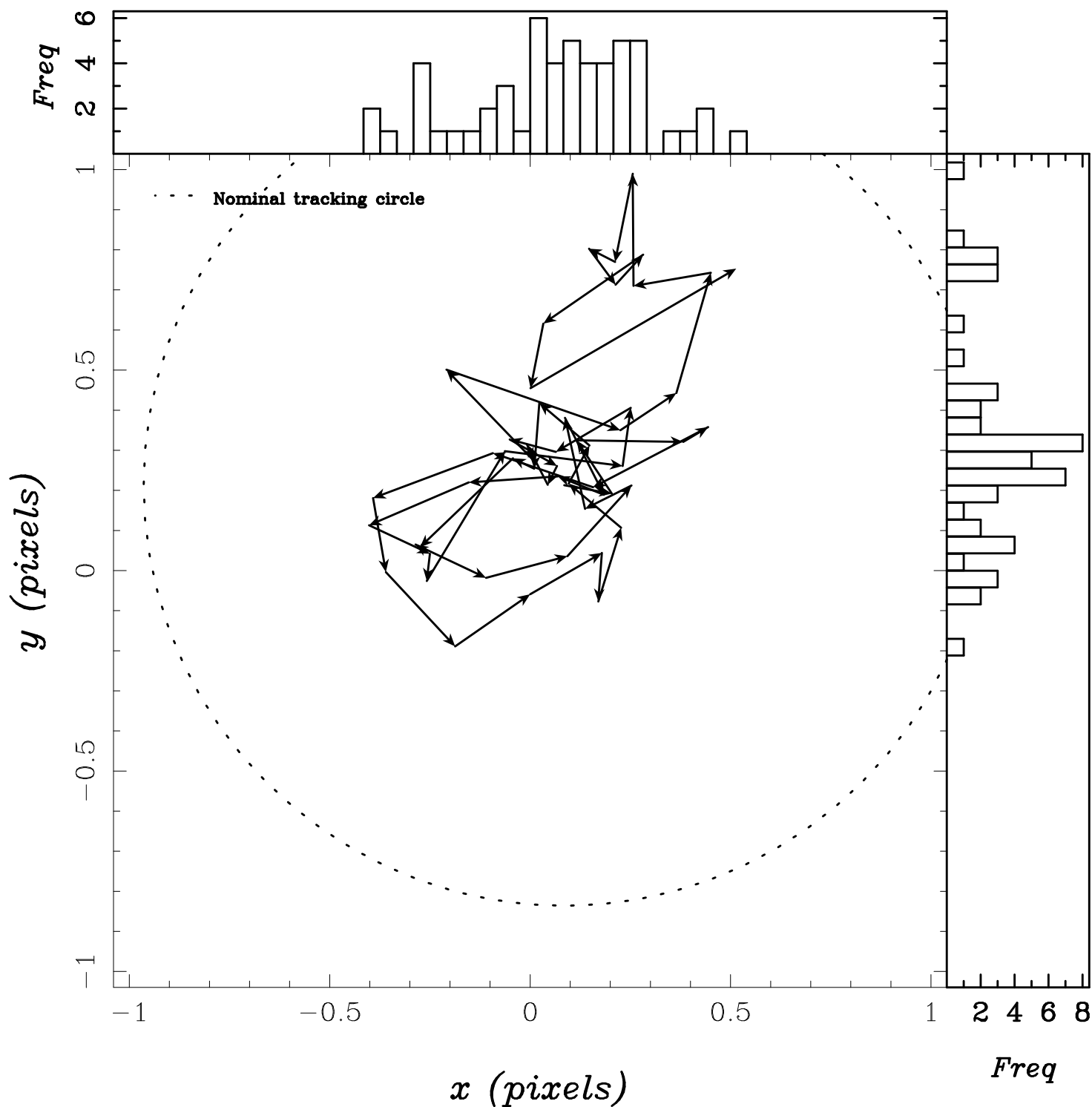


OM tracking history plot– object 252P/LINEAR

Observation ID: 0763940536
Exposure ID: 0763940536406
Filter UVW1 Plate-scale=0.4765 arcsecs/pixel
Tracking frame time: 20.0 secs
Number of good tracking frames: 54
Number of bad tracking frames: 0

Tracking history vector plot



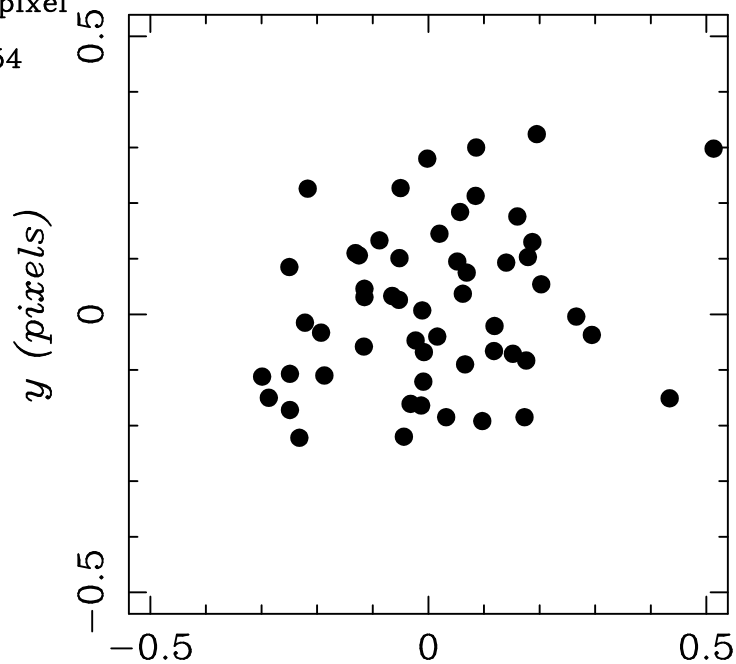
OM tracking history plot– object 252P/LINEAR

Observation ID: 0763940536
 Exposure ID: 0763940536406
 Filter UVW1 Plate-scale=0.4765 arcsecs/pixel
 Tracking frame time: 20.0 secs
 Number of good tracking frames: 54
 Number of bad tracking frames: 0

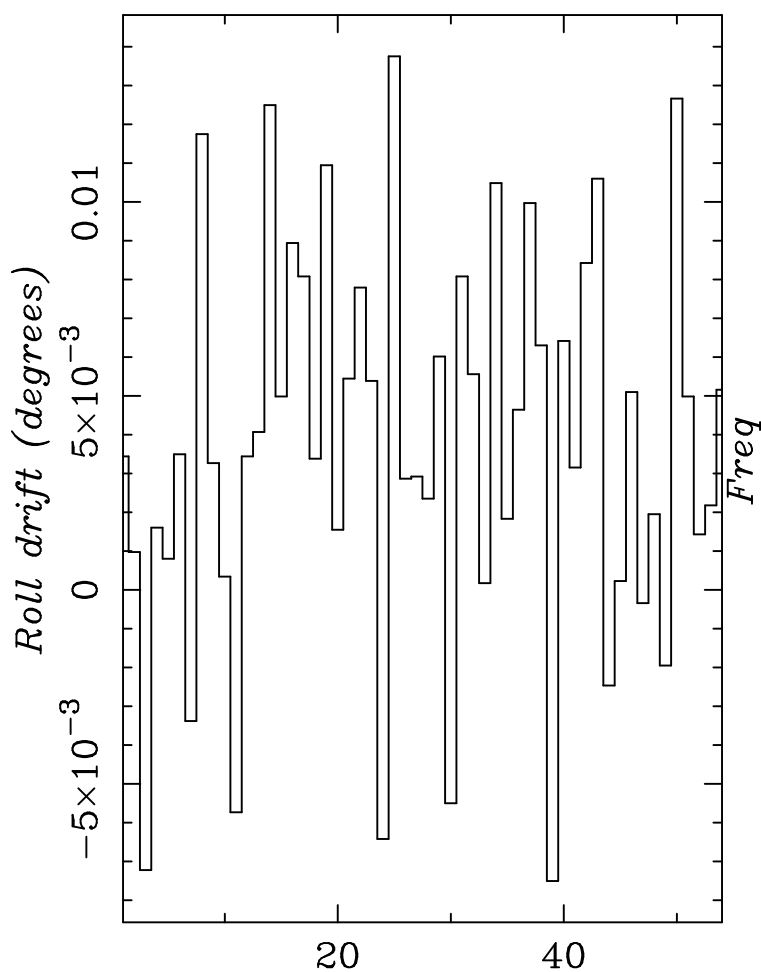
Percentage of excursions
 outside 1.0 pixels: 0.0 %

Mean drift per tracking
 frame (pixels): 0.2

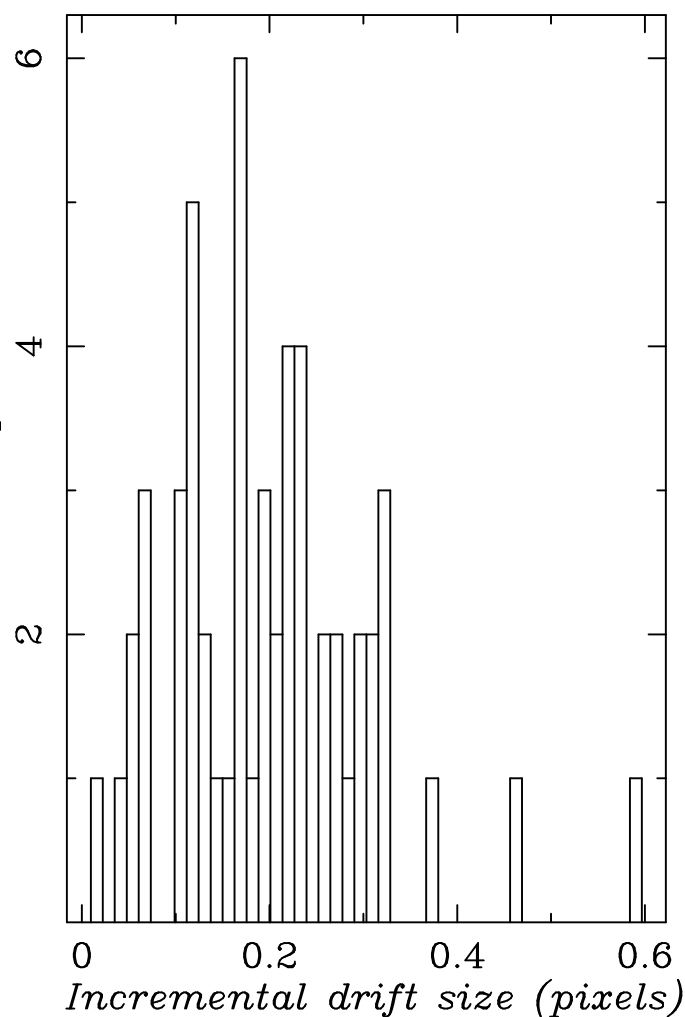
Incremental drift spot diagram



Roll drift plot



Frame number



Incremental drift size (pixels)